NUMERICAL INVESTIGATION OF THE PROCESS OF THE SUDDEN EJECTION OF A WORKED COAL SEAM
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The initial stage of the ejection of coal before the breakthrough of the broken-down gas coal mass into the working space is characterized by the rapid forcing out of the plastic zone of the coal near the end face. In the case of a small intensity, the ejection is damped in the initial stage, limited by the sudden forcing out of the worked coal seam.

In [1] a model of the sudeen forcing out of a worked coal seam was constructed. As unknown parameters characterizing the forcing out process there were taken the coordinate of the end face $x_{1}$, the coordinates of the beginning and the end of the zone of pulverized coal $x_{2}$ and $x_{3}$, and the coordinate of the boundary of the plastic zone $x_{4}$ (Fig. 1). Retaining the notation of [1], we write the system of equations describing the ejection process. It consists of relationships expressing the condition of the conservation of mass for three sections of the plastic zone

$$
\begin{align*}
& \int_{x_{i}}^{x_{i+1}} v(x) d x=\int_{x_{i}^{0}}^{x_{i+1}^{0}} v^{0}(x) d x+\beta_{i} \int_{x_{4}^{0}}^{x_{i}^{\prime}} h d x,  \tag{1}\\
& \beta_{i}=0 \text { for } i=1,2, \beta_{i}=1 \text { for } i=3,
\end{align*}
$$

and the relationships

$$
\begin{gather*}
\gamma H \pi+A\left\{\left[x_{2}\left(x_{4}-x_{2}\right)\right]^{1 / 2}-\left[x_{1}\left(x_{4}-x_{1}\right)\right]^{1 / 2}\right\}-A_{1}\left[x_{3}\left(x_{4}-x_{3}\right)\right]^{1 / 2}+ \\
+\left(A x_{4}+2 B\right)\left[\operatorname{arctg}\left(x_{4} x_{2}^{-1}-1\right)^{1 / 2}-\operatorname{arctg}\left(x_{4} x_{1}^{-1}-\right.\right. \\
\left.-1)^{1 / 2}\right]+2 P\left[\operatorname{arctg}\left(x_{4} x_{3}^{-1}-1\right)^{1 / 2}-\operatorname{arctg}\left(x_{4} x_{2}^{-1}-1\right)^{1 / 2}\right]-\left(A_{1} x_{4}+2 B_{1}\right) \operatorname{arctg}\left(x_{4} x_{3}^{-1}-1\right)^{1 / 2}=0  \tag{2}\\
h=\left(1-v^{2}\right) E^{-1}\left\{-(1 / 2) M x_{4}^{2}-\left[x_{2}\left(x_{4}-x_{2}\right)\right]^{1 / 2}\left[(1 / 2) A\left(2 x_{2}+x_{4}\right)+2 B-2 P\right]+\right. \\
\left.+\left[x_{1}\left(x_{4}-x_{1}\right)\right]^{1 / 2}\left[(1 / 2) A\left(2 x_{i}+x_{4}\right)+2 B\right]+\left[x_{3}\left(x_{4}-x_{3}\right)\right]^{1 / 2}\left[(1 / 2) A_{1}\left(2 x_{3}-x_{4}\right)+2 B_{i}-2 P\right]\right\} \tag{3}
\end{gather*}
$$

containing the unknown parameters $x_{1}, x_{2}, x_{3}, x_{4}, x_{4}^{\prime}$, and $P$. In Eqs. (1) the vertical shift $v(x)$ of the rock-coal interface is determined by the Kolosov-Muskhelishvili formulas [2] and the complex functions $\Phi(z)$ and $\Omega(z)$ given by the relationships (3.7) of [1]. The values of the corresponding coordinates at the moment of time $t=0$ are designated in terms of $x_{i}^{\circ}$. The function of the vertical shift in each section of the integration $v^{\circ}$ coincides with the form of the function $v$, the balues of $x_{1}, x_{2}, x_{3}, x_{4}$, and $P$ being replaced by $x_{1}^{0}, x_{2}^{0}$, $x_{3}^{0}$, $x_{4}^{0}$, and $P^{0}$. We note that the relationships (2) and (3) remain true at the initial moment of the ejection $t=0$.

In Eqs. (1)-(3) the coefficients $M, A, B, A_{1}$, and $B_{1}$ are determined by the formulas

$$
\begin{gathered}
M=A \operatorname{arctg}\left(x_{4} x_{2}^{-1}-1\right)^{1 / 2}-A \operatorname{arctg}\left(x_{4} x_{1}^{-1}-1\right)^{1 / 2}-A_{1} \operatorname{arctg}\left(x_{4} x_{3}^{-1}-1\right)^{1 / 2}, \quad A=\tau_{s} h^{-1}, \\
B=k\left[\left(1-\tau_{s}^{2} k^{-2}\right)^{1 / 2}+k \tau_{s}^{-1} \arcsin \left(\tau_{s} k^{-1}\right)\right]-\tau_{s} x_{1} h^{-1}, \\
A_{1}=k h^{-1}, B_{1}=k\left(\pi / 2+p / k-x_{3} / h\right) .
\end{gathered}
$$

By $s$ we denote the absolute shift of the plug ( $x_{1}, x_{2}$ ). The shift $s$ is connected with the coordinates $X_{4}$ and $x_{2}$ by the relationship

$$
\begin{equation*}
s=\left(x_{4}-x_{2}\right)-\left(x_{4}^{\prime}-x_{2}^{0}\right) . \tag{4}
\end{equation*}
$$

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Fig. 1


Fig. 2

We close the system of equations (1)-(4) by adding to it the equation of the motion of the plug in the form

$$
\begin{gather*}
\ddot{m s}=P_{v}\left(x_{2}\right)-\tau_{s}\left(x_{2}-x_{1}\right),  \tag{5}\\
m=\gamma g^{-1} \int_{x_{1}}^{x_{2}} v(x) d x .
\end{gather*}
$$

Equation (5) is integrated taking account of the conditions

$$
s=0, d s / d t=0 \text { for } t=0
$$

With the numerical solution of the differential equation (5), in each stage of the integration with respect to the time the system of transcendental equations (1)-(4) is solved. We note that for a given value of the shift $s$, the system of equations (1)-(4) will be closed with respect to the values of $x_{1}, x_{2}, x_{3}, x_{4}, x_{4}^{\prime}$, and $P$ [3]. This system can be solved numerically by the method of differentiation with respect to the parameter $s$ [4]. Assuming that $x_{1}, x_{2}, x_{3}, x_{4}, x_{4}^{\prime}$, and $P$ are functions of the shift $s$, we differentiate relationships (1)-(4) with respect to $s$ and convert them to the form

$$
\begin{equation*}
\frac{d \bar{x}_{i}}{d \bar{s}}=\frac{D_{i}}{D}, \quad \frac{d \bar{P}}{d \bar{s}}=\frac{D_{5}}{D}, \quad \frac{d \bar{x}_{4}^{\prime}}{d \bar{s}}=\frac{D_{6}}{D}, \quad i=1,2,3,4 \tag{6}
\end{equation*}
$$

By $D, D_{i}, D_{5}$, and $D_{6}$ we denote determinants of the sixth order.
The system of equations (1)-(5) and the boundary conditions were brought into dimensionless form by dimensionless parameters introduced in the following manner:

$$
\begin{gathered}
\bar{x}_{i}=x_{i} / h, \bar{x}_{4}^{\prime}=x_{4}^{\prime} / h, \quad \bar{v}=v / h, \quad \bar{s}=s / h \\
\bar{P}=P / \gamma H, \bar{k}=k / \gamma H, \tau_{s}=\tau_{s} / \gamma H \\
\widetilde{\approx}_{k}=k\left(1-v^{2}\right) / E, \bar{\tau}_{s}=\tau_{s}\left(1-v^{2}\right) / E .
\end{gathered}
$$

(Below, all quantities having the dimensions of length will be referred to half the thickness of the coal seam h.)

The system of equations (6) was integrated numerically by the Runge-Kutta method in the segment $0 \leqslant s \leqslant s_{k}$ with the initial values

$$
\mathrm{x}_{1}=x_{1}^{0}, x_{2}=x_{2}^{0}, x_{3}=x_{3}^{0}, x_{4}=x_{4}^{\prime}=x_{4}^{0}, \quad P=P
$$

Formula (4) determines the absolute shift of the cross section $x_{2}$. Numerical integration of the system of equations (6) shows that not every positive shift s (motion of the cross section $x_{2}$ to the left) corresponds to a positive shift of the cross section $x_{1}$. Since we are interested in the ejection of the end-face plug into the working space, i.e., a shift of the cross section $x_{2}$ to the left, it is convenient to introduce into the discussion the quantity $s_{2}$, which is the absolute shift of the cross section $x_{2}$ :

$$
s_{i}=\left(x_{4}-x_{i}\right)-\left(x_{4}^{\prime}-x_{1}^{0}\right)
$$

With replacement of Eq. (4) by Eq. (7), the system (6) retains its form, with the exception of the sixth row of the determinants.

The changes in the values of $s, s_{1}, x_{1}, x_{2}, x_{3}, x_{4}$, and $P$ with an increase in the shift of the cross section $x_{1}$ are given in Table 1 for the following numerical values of the parameters: $\bar{k}=0.2, \bar{\tau}_{s}=0.18, \mathrm{E} / \mathrm{k}=2000$, and $\nu=0.2$. The initial parameters of the process

TABLE 1.

| $\overline{s_{1}}$ | $\bar{s}$ | $\bar{x}_{1}$ | $\bar{x}_{2}$ | $\bar{x}_{3}$ | $\bar{x}_{4}$ | $\overline{\mathbf{P}}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 119,24 | 127,24 | 137,24 | 144,36 | 3,42 |
| 0,4 | 0,26 | 118,80 | 126,93 | 137,10 | 145,34 | 3,14 |
| 0,8 | 0,53 | 118,37 | 126,64 | 136,97 | 146,23 | 2,89 |
| 1,2 | 0,80 | 117,95 | 126,35 | 136,83 | 147,05 | 2,67 |
| 1,6 | 1,07 | 117,53 | 126,06 | 136,70 | 147,80 | 2,47 |
| 2,0 | 1,35 | 117,13 | 125,78 | 136,57 | 148,49 | 2,29 |
| 2,4 | 1,63 | 116,73 | 125,50 | 136,44 | 149,14 | 2,12 |
| 2,8 | 1,90 | 116,33 | 125,23 | 136,32 | 149,75 | 1,96 |
| 3,2 | 2,18 | 115,94 | 124,96 | 136,20 | 150,32 | 1,82 |
| 3,6 | 2,46 | 115,51 | 124,69 | 136,08 | 150,86 | 1,68 |
| 4,0 | 2,74 | 145,26 | 124,49 | 135,99 | 151,24 | 1,58 |

of sudden ejection for the above values of the parameters $\bar{k}, \bar{\tau}_{S}, E / k$, and $\nu$ were determined by the solution of the system of equations (3.9), (3.10), (3.12), and (3.13) of [1]. They are given in the first row of Table 1 . The length of the plug $l_{12}^{0}$ at the initial moment of the ejection was taken equal to eight, and the length of the zone of broken-down coal $Z_{32}^{\circ}$ was taken to 10 h .

Calculations show that with a displacement of the plug, the shift of the cross section $x_{1}$ is 1.6 times as great as the shift in the cross section $x_{2}$, although this figure decreases somewhat with an increase in the sift of the cross section $x_{1}$; as a rule, it remains around 1.4 for real values of the shift of the cross section $x_{1}\left(s_{1}<12 h\right)$. In the case where with a break in the adhesion at the contact surface between the ejected plug and the rock there is established a value of the tangential stress $\tau_{s}$ considerably less than the value of $k$, the ratio of the shifts $s_{1} / \mathrm{s}$ practically does not change. Thus, with the above values of the parameters $\bar{k}, E / k$, and $v$ and a value of $\bar{\tau}_{s}$ equal to 0.09 , the value of the ratio $s_{1} / s$ rises by $0.3-0.5 \%$. From Table 1 it can be seen that the ejection of the plug is accompanied by a certain hollowing out of its leading part, in contact with the free surface.

In view of this we write the equation of the motion of the center of gravity of the plug in the form

$$
\begin{equation*}
m \ddot{s_{c}}=p_{v}\left(x_{2}\right)-\tau_{s}\left(x_{2}-x_{1}\right) \tag{8}
\end{equation*}
$$

where, the shift in the center of gravity of the plug $s_{c}$ is connected with the coordinates $X_{4}$ and $x_{4}$ by the relationship

$$
\begin{equation*}
s_{c}=\left(x_{4}-x_{c}\right)-\left(x_{4}^{\prime}-x_{c}^{0}\right), \tag{9}
\end{equation*}
$$

in which $x_{c}$ denotes the coordinates of the center of gravity of the plug, determined by the formula

$$
\begin{equation*}
x_{c}=\frac{\int_{x_{1}}^{x_{2}} x v(x) d x}{\int_{x_{1}}^{x_{2}} v(x) d x} \tag{10}
\end{equation*}
$$

Solving the system of equations (6), we determine the dependence of $x_{1}, x_{2}, x_{3}, x_{4}$, and $P$ on $s_{1}$. Consequently, the right-hand side of formula (8) will be a known function of $s_{1}$, and with the use of relationships (9) and (10), it becomes a known function of $s_{c}$. Therefore, we write (8) in the form

$$
\begin{equation*}
\ddot{s}_{c}=\omega\left(s_{c}\right) . \tag{11}
\end{equation*}
$$

Integrating (11) with the condition of the equality to zero at the initial moment of the ejection $t=0$ of the shift in the center of gravity and the velocity of the plug, we find the velocity of the motion of the plug,

$$
u_{\mathrm{p}}=\left(2 \int_{0}^{s} \omega(s) d s\right)^{1 / 2},
$$

and the time of its ejection,


Fig. 3


Fig. 4

$$
t_{\mathrm{f}}=\int_{0}^{s_{\mathrm{f}}} \frac{d s}{\left(2 \int_{0}^{2} \omega\left(s_{\mathrm{j}}\right) d s_{\mathrm{i}}\right)^{1 / 2}}
$$

The value of the shift in the center of gravity of the plug $s_{f}$ at the moment of the end of the process $t_{f}$ is determined by the condition of the reversion of the velocity of the motion of the plug to zero:

$$
\int_{0}^{s_{\mathrm{f}}} \omega(s) d s=0 .
$$

Figures 2 and 3 show the change in the shift $s_{c}$ and the velocity of the plug with time; in the calculations, instead of the equation of motion (8), the following more general equation of motion of the plug was considered:

$$
m \ddot{s_{\mathrm{c}}}=\alpha_{\mathrm{t}} P_{v}\left(x_{2}\right)-\tau_{s}\left(x_{2}-x_{1}\right)
$$

into which there is introduced the coefficient of transmission of the stresses $\alpha_{t}$, equal to unity in the case where the transmission of the stresses in the zone of fractured coal corresponds to the distribution of the pressure in an ideal incompressible fluid. With application to our problem, the lower boundary of $\alpha_{t}$ is determined from the condition

$$
\alpha_{\mathrm{t}}^{*} P^{0} v^{0}\left(x_{2}\right)-\tau_{s}\left(x_{2}^{0}-x_{1}^{0}\right)=0 .
$$

With $\alpha_{t}$ equal to $\alpha_{t}^{*}$, the plug remains in a state of rest. From Figs. 2 and 3 it can be seen that, with a change in $\alpha_{t}$ from 0.6 to 1 , the shift of the center of gravity of the plug does not exceed 4 h , the ejection time of the plug lies within the limits of $76-78 \mathrm{msec}$, and the maximal velocity of the plug varies from 12 to $82 \mathrm{~m} / \mathrm{sec}$. Numerical values are given for the following values of the parameters characterizing the physicomechanical properties of the rock and the coal: $\gamma=2.5 \mathrm{~g} / \mathrm{cm}^{3} ; \nu=0.2 ; \rho=1.3 \mathrm{~g} / \mathrm{cm}^{3} ; \mathrm{k}=0.2 ; \bar{\tau}_{\mathrm{s}}=0.18 ; \mathrm{E} / \mathrm{k}=2000$; $h=1 \mathrm{~m}$; and $H=1000 \mathrm{~m}$.

As is well known, solution of the problem with the condition of the closing of the lateral rock surrounding the coal seam gives a great extension of the hanging roof of the working space (see Table 1). In the practice of the working of coal seams, the hanging roof, as a rule, rests on caved-in layers of rock. We denote the thickness of the caved-in layers of rock by $2 \lambda$ h (see Fig. 1). Taking account of the caved-in layers of rock does not, in principle, introduce any difficulties into the statement of the problem under consideration. The system of equations (1), (2), (8)-(10) describing the ejection process retains its form completely; the quantity $h$ in the right-hand side of $\mathrm{Eq} .(3)$ is replaced by ( $1-\lambda$ )/h. In this case, the proposed calculating methods were used without any kind of changes. The results of the numerical calculations, given in Table 1 and in Figs. 2 and 3, correspond to a value of the parameter $\lambda$ equal to zero. Table 2 gives the initial parameters of the process of ejection for $\lambda=0.4$ and 0.6 . From the table it can be seen that, with an increase in $\lambda$, there is a certain decrease in the extension of the end-face plastic zone and a considerable decrease in the length of the hanging roof.

The form of the coal seam in the end-face plastic zone at the initial moment of ejection $t=0$ is shown in Fig. 4. On the vertical axis there is plotted the distance from the axis of symmetry of the coal seam to the contact surface between the coal seam and the rock. Curve 1 was plotted for a value of the coefficient $\lambda$ equal to zero. Curve 2 corresponds to a value of the parameter $\lambda$ equal to 0.4 . Taking account of the layers of caved-in rock leads to less deformation of the end-face zone of the coal seam.

TABLE 2

| $\lambda$ | $l_{32}^{0}$ | $\iota_{12}^{0}$ | $x_{1}^{0}$ | $x_{2}^{0}$ | $x_{3}^{0}$ | $x_{4}^{0}$ | $p^{0}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0,4 | 10 | 8 4 | 69,26 70,65 | 77,26 74,65 | $\begin{aligned} & 87,26 \\ & 84,65 \end{aligned}$ | 89 89 | 3,67 3,23 |
| 0,6 | 8 10 | 8 4 | 43,72 45,57 | 51,72 49,57 | 59,72 59,57 | 61,38 61,40 | 3,21 3,12 |



Fig. 5


Fig. 6

Taking account of the effect of the layer of caved-in rock should obviously have a considerable effect on the value of the length of the plug $\tau_{12}$ and on the zones of fractured coal $l_{32}$ formed at the initial moment of the ejection $t=0$. If we examine the case corresponding to equal values of $Z_{12}^{0}$ as well as $Z_{32}^{0}$, for $\lambda=0$ and $\lambda=0.4$, then a calculation of the process of the ejection of the plug shows that for $\lambda=0.4$ the ratio of the quantities $s_{1} / s$ remains practically the same for $\lambda=0$; the maximal velocity of the ejection for $\alpha_{t}=1$ increases to $88 \mathrm{~m} / \mathrm{sec}$; the time of the process decreases by $6-7 \mathrm{msec}$. From a comparison of the above values for $\lambda=0$ and $\lambda=0.4$ it can be seen that for identical lengths $Z_{12}^{\circ}$ and $Z_{32}^{\circ}$, taking account of $\lambda$ does not, in principle, introduce any changes into the character of the process of ejection.

Figure 5 shows the change in the length of the plug and the zone of fractured coal in the ejection process for $\bar{Z}_{12}^{0}=8, \bar{\gamma}_{32}=4$, and $\alpha_{t}=1$. The length of the end-face plastic plug with the selected values of the parameters characterizing the physicomechanical properties of the rock and the coal increases considerably during the ejection process (curve 1). The length of the zone of fractured coal (curve 2) also rises with the passage of time; the increase in $Z_{32}(t)$ is accompanied by a decrease in the value of the load in the ejection process. The solid curves in Fig. 5 correspond to $\lambda=0$, while the dashed curves correspond to $\lambda=0.4$.

If the lengths of the plug and the zone of fractured coal at the moment of the end of the ejection process are known, we can determine their lengths at the initial moment, using an algorithm developed for calculating the process and plotting a series of graphs of the change in $Z_{12}$ and $Z_{32}$ as a function of the time $t$.

In conclusion, let us examine the considerations on the basis of which the values of $Z_{12}$ and $Z_{32}$ at the initial moment of ejection $t=0$ can be determined. In [5, 6] it is shown that the fracturing of a coal seam with a sharp displacement of the maximum of the stressstrain diagram of the normal stresses into the depths of the massif can start in a section in which the gas pressure will exceed the normal stress $\sigma_{\mathrm{x}}$, as a result of which the stressstrain diagram of the gas pressure cannot be reconstructed with the rate of redistribution of the stresses in the massif. To the left of the point of intersection of the stresstrain diagrams (Fig. 6) the coal will be in an unfractured state. The distance from the end face can, in the first approximation, be taken as the length of the plug at the initial moment of the process of sudden ejection. The process of pulverization of the coal, continuing for a period of $2-3 \mathrm{msec}$, leads to the formation of a zone of fractured coal. The cross section in which the stress $\sigma_{x}$ is equal to the pressure of the gas at infinity can be taken as the boundary of the zone of fractured coal; for $x>x_{3}$, the stress $\sigma_{x}$ is greater than the pres-
sure of the gas at infinity $p_{\infty}$. Averaging the normal component of the stress along the zone of fractured coal, we obtain a discontinuity in the stress-strain diagram of the normal stresses in the cross section $x_{2}$. The value of this discontinuity $\delta$, determined by the relationship

$$
A x_{2}+B=P+\delta
$$

will lie within the limits

$$
0<\delta<p_{\infty}-\left.\sigma_{x}\right|_{x=x_{2}}
$$

For the selected values of the discontinuity $\delta$, the initial parameters of the process of sudden ejection can be determined by the method proposed in [3].

The gas-coal mixture expelling the plug is situated in a tube of variable diameter $v(x)$ (see Fig. 4). In the case of a breakdown of the plug, the gas-coal mixture will be carried out through the opening into the working space. The gasdynamic stage of the course of the ejection, before and after the breakthrough of the plug, must be considered, taking account of the contracting form of the working space, formed by the action of the stressed state around the working, varying during the course of the process.

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heat and mass transfer during an explosion in solids
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The pressures in the detonation products of explosives have a magnitude of the order of 100 kbar , and the temperature of the gases at the initial instants reaches several thousands of degrees. Many actual solids, soils, and rocks contain in their structure a considerable amount of pores, micro- and macroscopic cracks, and gaps separating the medium into individua: blocks. With these conditions, a gas having a high velocity can penetrate into these defects of the medium without performing any mechanical work in general on the deformation of the material or, with defined conditions, producing a "wedge" effect in the cracks. Since the freshly formed surfaces of solids have an enhanced sorption capability, part of the gas may be adsorbed into the medium and may undergo capillary condensation. The quantity of gas "absorbed" by the medium can be different depending on the total surface area of the cracks and pores and, in certain cases, can reach very considerable magnitudes. From a formal point of view, the entrainment of detonation products by solid media amounts to a nonadiabatic process of expansion of the explosion cavity in soils and rocks, while from the factual point of view it amounts to a reduction of the explosion efficiency or of its mechanical action.

In the Institute of Terrestrial Physics, Academy of Sciences of the USSR, under the directorship of $I$. L. Zel'manov, over the period of a number of years systematic experimental investigations have been conducted of microexplosions in sand with a different density of

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